

Unsteady pulsed jets using pneumatic valves for flow separation control: effect of internal acoustic waves on external flow structure

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- Interest in Aerodynamics of square-back bodies
- Recent projects on flow control for drag reduction with fluidic injection
 → Use of synthetic or pulsed jets at 2D and 3D model rear combined with flaps.
- Definition of a new model under the framework of Activ_ROAD program (ANR) to study the effects of flow control on simplified personal cars and trucks.











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- Fast-response actuator : high-frequency periodic or non-periodic time evolution of velocity,
- o Manageable DC : reduction of flow control cost
- Basic set-up for pulsed jet generation



Some typical results obtained

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80

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100 200 300 400 f_{ac} [Hz]

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60 U_j (m.s⁻¹) • Joseph et al. 40 Exp.in Fluids, 2012 20 f=200 Hz 0 1.005 1.01 1.015 1.02 1.025 1.03 1.035 1.045 1.05 1 1.04 Time (s) 4 DC = 40%DC = 50%3 3 Barros et al. V_j/V_j $\mathbf{2}$ JFM, 2016 1 f = 610 Hz, 0 0 Ó 0.02 Ó 0.01 0.02t (s) t (s) P [bar] PhD Thesis, M.Szmigiel, LMFA 100 200 300 400 f_{ac} [Hz]

What physical mechanism(s) may have such an influence on the pulsed jet characteristics?

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Outline

Experimental set-up

- Pneumatic setup
- ② Valve and control board
- 6 Flow measurements

2 Results

- 1 Illustration of typical results
- Processing using dimensionless parameters
- 8 Basic modeling

Conclusions

• Pneumatic set-up



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• Pressure measurements upstream of the valve (Kulite ETL-1-140)

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- Pressure measurements upstream of the valve (Kulite ETL-1-140)
- Velocity measurements at the nozzle exit (Dantec 55P01 probe and Dantec miniCTA)

Typical result for an actuation frequency of 10 Hz



- Noticeable oscillations on pressure and velocity signals, vanishing at the end of each phase (opening or closing)
- Peculiarity of hw signal at closing : rectified waveform
- For each phase, differences in oscillation frequency between the flow upstream and downstream the valve.
- For each location (downstream/upstream), fixed oscillation frequency.

Test-cases for identification of internal acoustic waves

Nine different configurations

- with variation in inlet pressure Pin, Lup and Ldown
- at fixed duty-cycle (50%) and actuation frequency (10 Hz)



P _{in} [barA]	L _{up} [mm]	L _{down} [mm]						
2.5	450				185		210	250
2.88	206	155	169	177		200		
3.7	206	155		177				

 \rightarrow Normalization possible between the different results obtained by varying $P_i n$, L_{down} and L_{up}

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Identification of a time delay



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 → valve working principle : closing is obtained by pressure force (pneumatic spring)
- at opening, the time delay is independent of $P_{
 m in}$,

 \rightarrow Opening of the valve done by the electromechanical force of the solenoid, thus delay less sensitive to pressure

Time delay modelling



• time delay in velocity signals increases linearly with the downstream length $L_{\rm down}$ for a given pressure.

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Good match with time delays identified from experimental data

Normalization



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- the amplitude of the first peaks of pressure (resp. velocity) are :
 - o nearly proportional to P_{steady} (resp. V_{steady}),
 - o independent of the lengths of the connecting pipes,
- the oscillation damping coefficient is independent of the inlet pressure and the lengths $L_{\rm down}$ and $L_{\rm up}.$

Pressure oscillations upstream of the valve





Modelling

Good agreement between the experiments and the closed-end tube model (max. deviation of 5% in estimation of f_1)



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After opening



$$f_{n} = (n) \frac{c}{2L_{up}}; \quad f_{1} = \frac{c}{2L_{up}}$$



Modelling



Modelling

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Velocity oscillations downstream of the valve



• 'Simpler' case : sonic section in the valve such that Closed-end tube model is relevant

Estimation of equivalent pipe length taking the nozzle geometry into account not straightforward.
 Good agreement between the experiments and the closed-end tube model (max. deviation of 8% in estimation of f₁)

Modelling of damping

Two possible sources of damping :

- Acoustic radiation
- Viscous effects



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Modelling* of the damping coefficient lpha (in time) after closing :

$$\alpha = \sqrt{\frac{\omega d}{2r}} \left(1 + \sqrt{\frac{\chi}{\nu}} \left(\frac{C_p}{C_v} - 1 \right) \right)$$

where d can be seen as a 'penetration depth' for viscous effects. For zero-mean flows,

$$d = \sqrt{\frac{2\nu}{\omega}}$$

(*) Moloney & Hatten, American Journal of Physics, 2001

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Modelling of damping

Estimation of logarithmic decrement δ : experiments (symbols)/ model (solid line) :



Confirmation of viscous effects as predominant cause of damping

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• Conclusions

- Existence of pressure (acoustic) waves in pipes upstream and downstream of the valve in a pulsed jet system.
- Decoupling of the pressure waves upstream and downstream of the valve.
- Oscillation frequency well approximated by closed-end tube model.

• Future work

- At high actuation frequencies, complex interactions between acoustic waves generated at opening with waves generated at closing,
- Resonance if actuation frequency is close to the acoustic waves frequency : possible optimization for large blowing velocity peaks at constant inlet pressure.
- Very different blowing velocity patterns at the nozzle exit can be achieved when varying DC or actuation frequency around .

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